

Minghsin University of Science and Technology

Syllabus for Elective Courses

| | | | |
|--|---|---------|---|
| Course Title | Theory of Gearing and its Applications | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Chung-Biau Tsay | | |
| Course Objective | This course offers the graduate students to facilitate the modern theory of gearing, and then students can apply the theory to the profile design, contact simulation and transmission analysis of the conjugate kinematic pairs, such as gears, cams, pumps, etc.. The course also promotes the students to understand the characteristics of the conjugate kinematic pair, and enables students to perform the related research problems. | | |
| Text Book | Faydor L. Litvin, “Gear Geometry and Applied Theory” , Prentice Hall, 1994. | | |
| Reference Books | 1. Faydor L. Litvin, “Theory of Gearing” , NASA Reference Publication 1212, Washington D. C., 1989. 2. Faydor L. Litvin, and Alfonso Fuentes, “Gear Geometry and Applied Theory” , Cambridge University Press UK, 2004. | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. Course introduction, contents review2. Chapter1. Coordinate Transformation.3. Chapter1. Coordinate Transformation.4. Chapter2. Transformation of Motion.5. Chapter2. Transformation of Motion.6. Chapter3. Planar Curves.7. Chapter3. Planar Curves.8. Midterm Exam9. Chapter4. Conjugate Shapes.10. Chapter4. Conjugate Shapes.11. Chapter5. Gearing Analysis (Tooth Contact Analysis.)12. Chapter5. Gearing Analysis (Tooth Contact Analysis.)13. Project study: Gear Design and Analysis14. Chapter6. Basic Kinematic Relations of Gearing and Their Applications.15. Chapter6. Basic Kinematic Relations of Gearing and Their Applications.16. Chapter6. Basic Kinematic Relations of Gearing and Their Applications.17. Chapter7. Generation of Conjugate Shapes.18. Final Exam | | | |

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Syllabus for Elective Courses

| | | | |
|--|--|---------|---|
| Course Title | Advanced Kinematics | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Fu-Hua Jen | | |
| Course Objective | Instruct students to learn knowledge in advanced kinematics. It includes kinematics synthesis, kinematics analysis, | | |
| Text Book | | | |
| Reference Books | 1 A.G. Erdman, Modern Kinematics, Wiley, 1993. 2 R.S. Hartenberg and J. Denavit, Kinematic Synthesis of Linkages, | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. First example for design of mechanism2. Introduction to mechanical device3. Synthesis of linkage for multiple positions4. Analytical synthesis5. Analysis of kinematics6. Techniques for creative design7. Design methodology8. Generalizations of joints and links9. Generalizations of mechanical chain10. Kinematic chains11. Specializations for mechanism12. Topics | | | |

Minghsin University of Science and Technology

Syllabus for Elective Courses

| | | | |
|---|--|---------|---|
| Course Title | System Vibration | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Hsing-Hsin Huang | | |
| Course Objective | The purpose of this course is to study the subject of mechanical and structural vibration. Both the responses of free and forced vibration are discussed. The introduction starts from one degree of freedom system to complicated continuous models. Several measurement instruments and analysis software are also introduced to help students to gain more understanding of the concept of this course. | | |
| Text Book | “Mechanical Vibration analysis, uncertainties, and control” , Haym Benaroya, Prentice Hall, ISBN 0-13-948373-X | | |
| Reference Books | Technical Documentations of Bruel & Kjaer. | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. Introduction and Background2. Mathematics & Software3. Undamped Single DOF Vibration: Examples and Mathematical Modeling, Free Vibration w/o Damping, Harmonic Forced Vibration w/o Damping4. Damped Single DOF Vibration: Free Vibration w/h Damping, Harmonic Excitation and Damped Response, Examples5. Single DOF Vibration: Experiments and Signal Analysis6. State Variable Method and Simulation7. Principle of Virtual Work and Lagrange' s Equation8. Multi DOF Vibration: Examples and Derivation of Equation of Motion, Undamped Vibration and Forced Vibration by the Direct Method, Modal Analysis9. Multi DOF Vibration: Experiments and Signal Analysis10. Continuous Models for Vibration: Vibration of Strings, Shafts and Beams | | | |

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Syllabus for Elective Courses

| | | | |
|---|---|---------|---|
| Course Title | Image Inspection Technology | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Mu-Jung Chen | | |
| Course Objective | The main objectives of this course are to provide students with principles of optical inspection, digital image processing, hardware and program of image inspection, image inspection technology, and applications in industry automation. | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. Basic device and equipment of image inspection system2. CCD camera and geometrical optics3. Basic technologies of image processing, and program library4. Image filtering5. Image enhancement6. Image calibration7. Frequency domain analysis8. Particle measurements9. Edge detection and auto focus10. Pattern identification11. Dimensional measurements12. Shape measurements13. Defect inspection14. Applications of image inspection technology15. Case study of image inspection technology | | | |

Minghsin University of Science and Technology

Syllabus for Elective Courses

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|--|--|---------|---|
| Course Title | Advanced Computer-Aided Design | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Ming-Jong Wang | | |
| Course Objective | Teach students how to design machine elements, assembly the designed parts, and the dynamic simulation of assembled mechanism by using CAD software. | | |
| Text Book | Engineering Design and Graphics with Autodesk Inventor 2009 ISBN: 0-13-515762-5, James D. Bethune, Boston University, Autodesk, Autodesk, Inc. | | |
| Reference Books | | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. Introduction to CAD2. Create a 2-D sketch3. Three dimensional model4. The design process5. Assemblies6. Explosive view & its animation7. Mechanism animation8. Design projects | | | |

Minghsin University of Science and Technology

Syllabus for Elective Courses

| | | | |
|---|---|---------|---|
| Course Title | Laser Technology and Application | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Chi-nan Wang | | |
| Course Objective | This course introduces the basics and principles of laser material processing. Students will learn the laser technologies and its applications. | | |
| Text Book | Handouts | | |
| Reference Books | Laser Material Processing, William M. Steen Understanding Lasers-An Entry-Level Guide, Jeff Hetch | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. Introduction to Laser2. Laser Modes and Properties3. Laser Safety4. Mechanisms of Laser Material Processing5. Industrial Lasers6. Applications of Laser7. Characteristic of Laser System | | | |

Minghsin University of Science and Technology

Syllabus for Elective Courses

| | | | |
|-------------------|---|---------|---|
| Course Title | Computer I/O Interface Control | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Mowcheng Lee | | |
| Course Objective | To teach students computer IO and their interface control | | |
| TextBook | Class handout | | |
| Reference Books | http://www.google.com | | |

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|---|
| Class 1. Introduction to PC Architecture and Visual Basic |
| Class 2. Parallel port IO Interface--- part 1 |
| Class 3. Parallel port IO Interface--- part 2 |
| Class 4. Serial port IO Interface --- part 1 |
| Class 5. Serial port IO Interface --- part 2 |
| Class 6. Programmable interface 8255A and basic IO |
| Class 7. 8255A hand shake transmission |
| Midterm Examine |
| Class 8. 8253/8254 chips and counters |
| Class 9. D/A and A/D |
| Class 10. Step motor |
| Class 11. LCD |
| Class 12. USB |
| Class 13. Project and Discussion |
| Class 14. Project and Discussion |
| Class 15. Project and Discussion |
| Class 16. Project and Discussion |
| Final Examine |

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Syllabus for Elective Courses

| | | | |
|---|--|---------|---|
| Course Title | Linear System | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Hsing-Hsin Huang | | |
| Course Objective | Linear system is the basis of modern control. This class introduces the concept of a linear system, and discusses the I/O relation as well as the state information within a system The class also teaches MATLAB and LABVIEW software to help students to understand the industrial control technology. | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. Introduction2. Mathematical background of a linear system3. Introduction of MATLAB4. I/O description and state variable description of a system5. Dynamic analysis of a linear system6. Introduction of Labview7. Stability, Observability and Controllability8. State feedback controllers and estimators design | | | |

Minghsin University of Science and Technology

Syllabus for Elective Courses

| | | | |
|---|--|---------|---|
| Course Title | Laser metrology | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Mu-Jung Chen | | |
| Course Objective | The main objectives of this course are to provide students with principles of laser metrology, laser interferometers, laser measurement systems, fiber laser measurements, laser signal processing and applications. | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. Introduction to Laser metrology2. Fundamental optics and optical components3. Laser measurement system4. Laser sources, modulation and photo detectors5. Interference, diffraction, polarization and filtering6. Single/dual frequency laser interferometers7. Laser Doppler measurement8. Laser triangulation method9. Laser optical scales and grating techniques10. Laser holography11. Laser scanners and position sensitive detectors12. Fiber laser measurements13. Applications for precision machinery14. Computerized optical signal processing15. Case study | | | |

Minghsin University of Science and Technology

Syllabus for Elective Courses

| | | | |
|-------------------|---|---------|---|
| Course Title | Optimal Design | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Jie-Ren Shie | | |
| Course Objective | This course focuses on training students about how to design experiments and analyze data through the design of experiment approach so that they can optimize the process parameters and design through optimization schemes. | | |
| Text Book | Design and Analysis of Experiments 6/E | | |
| Reference Books | None | | |

Course Contents

| Topics | Abstract | Classes |
|---|---|---------|
| Introduction | Basic of DOE | 3 |
| One Factor DOE | 1. One factor design 2. Case study 3. Computer excises | 9 |
| Multiple Factor DOE | 1. Multiple factor design 2. Case study 3. Computer excises | 9 |
| Multiple Factor with Multiple Level DOE | 1. Multiple factor with multiple level design 2. Case study 3. Computer excises | 9 |
| Case Studies | 1. Case study (1) 2. Computer excise (1) 3. Case study (2) 4. Computer excise (2) | 6 |
| Response Surface Method (RSM) | 1. Introduction to RSM 2. Case study 3. Computer excises | 9 |
| Mixture Design | 1. Introduction to mixture design 2. Case study 3. Computer excises | 6 |
| Mixture with Process Design Method | 1. Introduction to mixture with process design method 2. Case study 3. Computer excises | 3 |

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Syllabus for Elective Courses

| | | | |
|---|---|---------|---|
| Course Title | Practice of Mechatronic System | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Jen-Chao Tai | | |
| Course Objective | 1. To be acquainted with the basic components of mechanical device 2. To be acquainted with the basic components of electronic device 3. To be acquainted with the Programmable Logic Controller 3. To be acquainted with the practice of mechatronic system | | |
| Course Contents | | | |
| 1. Introduction of the basic components of mechanical device 2. Introduction of the basic components of electronic/electrical device 3. Introduction of the basic components of pneumatic/hydraulic device 4. Introduction of the basic components of sensor device 5. Programmable logic controller and its application 6. Practice of vibrator feeding and quality inspection machine 7. Practice of automatic filling and Titration machine 8. Practice of pose inspection and assembly machines. 9. Practice of color identification and stacking machine 10. Practice of automatic storage and retrieval system | | | |

Minghsin University of Science and Technology

Syllabus for Elective Courses

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|-------------------|---|---------|---|
| Course Title | Precision Machine Design(II) | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Jen-Chang Lin | | |
| Course Objective | Concept of Design for machine elements in the machine | | |
| Text Book | Mechanical Design An Integrated Approach by Ansel C. Ugural | | |
| Reference Books | | | |

Course Contents

1. Bearing and Lubrication
2. Spur Gears.
3. Helical, Bevel, Worm Gears.
4. Belt, Chain, Clutch, Brakes
5. Design of Springs
6. Power Screws, Fasteners, and Connections
7. Design of Micro-Machines
8. Design of Competitive Robot

Minghsin University of Science and Technology

Syllabus for Elective Courses

| | | | |
|---|---|---------|---|
| Course Title | Computer-Aided Engineering – Case Study | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Hung-Yu Lu | | |
| Course Objective | Enforce the abilities of research and engineering analysis through the case study of computer-aided engineering. | | |
| Text Book | Handout posted in e-Campus (Minghsin e-learning system) | | |
| Reference Books | <ol style="list-style-type: none">1. Finite Element Analysis, Theory and Application with ANSYS /Saeed Moaveni2. Engineering analysis with ANSYS software / Y. Nakasone and S. Yoshimoto ; T.A. Stolarski.3. The finite element method and applications in engineering using ANSYS / by Erdogan Madenci, Ibrahim Guven. | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. Introduction to APDL.(ANSYS Parametric Design Program)2. Theory of Dynamic Analysis3. Introduction to Modal Analysis.4. Case study: Modal analysis of Frames and Wings.5. Introduction to optimization analysis6. Case study: Optimization design of Beams and Wrenches.7. Introduction to Nonlinear Analysis and Newton-Raphson Scheme.8. Case Study: Nonlinear analysis of curved beams.9. Case study: Structural analysis of beams under dynamic loading.10. Case study: Bi-metal thermo-structure coupled analysis.11. Case study: Thermal analysis of Chip-Scale package. | | | |

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Syllabus for Elective Courses

| | | | |
|--|--|---------|---|
| Course Title | Finite Element Method | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Hung-Yu Lu | | |
| Course Objective | <ol style="list-style-type: none">1. Understand the theory and concept of finite element.2. Practice various engineering problems by using ANSYS3. Increase research ability and career compatibility. | | |
| Course Contents | | | |
| <p>1. Introduction: Engineering Problems; 2.Numerical Methods; Basic Steps in the Finite Element Method; Finite Element Formulations: (1) Direct Formulation; (2) Minimum Total Potential Energy Formulation; (3) Weighted Residual Formulations.</p> <p>2. Trusses: Definition of a Truss; Finite Element Formulation; Examples using ANSYS: Plane Trusses, Space Trusses</p> <p>3. One-Dimensional Elements: Linear Elements, Quadric Elements, Cubic Element, Global, Local and Natural Coordinates, Numerical Integration: Gauss Legendre Quadrature.</p> <p>4. Analysis of One-Dimensional Problems: Heat Transfer Problems, Truss Analysis, Beam and Frame Analysis, Analysis Examples of using ANSYS.</p> <p>5. Two-Dimensional Elements: Rectangular Elements, Quadratic Quadrilateral Elements, Linear Triangular Elements.</p> <p>6. Analysis of Two-Dimensional Problems: Heat Transfer Problems, Plane Stress Problems, Heat Sink and Plane Stress Problems using ANSYS.</p> <p>7. Analysis of Three-Dimensional Problems: Thermal and Structural Example using ANSYS.</p> | | | |

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Syllabus for Elective Courses

| | | | |
|---|---|---------|---|
| Course Title | Advanced Quality Control | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Jie-Ren Shie | | |
| Course Objective | <ol style="list-style-type: none">1. Educate students to implement DMAIC (Define Measure Analyze Improve Control) Six Sigma methodology from General Electric Co. (GE) to efficiently resolve quality related issues.2. Train students to improve processes or designs through analyzing collected data. | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. Introduction to six sigma quality control2. Define phase:<ol style="list-style-type: none">a) project definition; b) Process map; c) Grantt chart; d) presentation skills; e) define phase report3. Measurement phase:<ol style="list-style-type: none">a) Fishbone; b) Failure Mode and Effect Analysis; c) Pareto chart; d) Quality Functional Deployment; e) Measurement System Analysis4. Analyze phase:<ol style="list-style-type: none">a) Capability indices; b) Benchmarking; c) Hypothesis tests5. Improve phase:<ol style="list-style-type: none">a) Introduction to Design of Experiments; b) Variety of process maps; d) Introduction to Design for Six Sigma6) Control phase:<ol style="list-style-type: none">a) Gage study; b) Risk analysis; c). Mistake proof; d) Statistical process control and control charts | | | |

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Syllabus for Elective Courses

| | | | |
|--|--|---------|---|
| Course Title | Practice of Computer Control System | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Jen-Chao Tai | | |
| Course Objective | 1. To be acquainted with the basic actuators of control devices 2. To be acquainted with the basic devices of sensors 3. To use PC or micro-controller to control the industrial equipment | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. Introduction of computer control system2. Introduction of single chip 80513. Digital input, digital output and sequential control4. Led matrix and key control5. timer and led matrix control6. Serial communication and PC program7. PLC sequential communication and PC program8. PC peripheral interface and program9. Introduction of PIC10. Registers of PIC11. Timer application of PIC12. AD conversion and DA conversion13. PWM output14. LCD control15. Serial and parallel communication16. I2C serial communication | | | |

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Syllabus for Elective Courses

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|-------------------|---|---------|---|
| Course Title | Modern Control Methods | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Hsin-Te Liao | | |
| Course Objective | To introduce methods for analysis of feedback control system characteristics, including performance and stability, and design of feedback control | | |
| Text Book | “Modern Control Systems” , Richard C. Dorf & Robert H. Bishop | | |

Course Contents

1. Introduction; Dynamic System Modeling
2. Block Diagram and Transfer Function
3. State Variable Models
4. Control System Characteristics
5. Measures of Performance
6. Stability: Routh - Hurwitz method
7. Root Locus Method
8. Frequency Response: Bode Diagrams
9. Stability: Nyquist Criterion
10. Design of Compensators
11. Controllability and Observability

Minghsin University of Science and Technology

Syllabus for Elective Courses

| | | | |
|---|---|---------|---|
| Course Title | Management of Technology | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Hansen T. Lee | | |
| Course Objective | 1. To integrate strategy and technology that today' s business required that is applicable to no matter what the educational background of the student may be. 2. To provide insight into the management of technology and innovation that will be useful to students as they enter practices. | | |
| Text Book | “The Management of Technology and Innovation” , Margaret A. White / Garry D. Bruton, ISBN : 0-324-35365-0 | | |
| Course Contents | | | |
| Chapter1. Management of Technology and Innovation | | | |
| Chapter2. Strategy and Management of Technology and innovation. | | | |
| Chapter3. Innovation : Planning | | | |
| Chapter4. Internal Innovation : Implementation | | | |
| Chapter5. Innovation : Evaluation and Control | | | |
| Chapter6. Obtaining Technology : Planning | | | |
| Chapter7. Obtaining Technology : Implementation | | | |
| Chapter8. Obtaining Technology : Evaluation and Control | | | |
| Chapter9. Building Capability : For MTI success | | | |
| Chapter10. Organizational Learning and Knowledge Management | | | |

Minghsin University of Science and Technology

Syllabus for Elective Courses

| | | | |
|---|--|---------|---|
| Course Title | Power Electronics Control System | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Ming-Fa Tsai | | |
| Course Objective | In this course, the materials about the controller and ASIC design of power electronic systems, such as buck and boost DC-DC converters, by using FPGA device and VHDL programming language are taught to the students with the help of MATLAB/Simulink simulation tool. | | |
| Text Book | “Fundamentals of Power Electronics (2nd Edition)” , Robert W. Erickson and Dragan Maksimovic, ISBN : 0-324-35365-0 | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. The Principle of Buck DC-DC Converter.2. Small-Signal Modeling of Buck Converter3. Controller Design of Buck Converter4. The Controller Circuit Design of the Buck Converter using VHDL5. Simulation Verification of the Buck Controller Circuit Design6. Small-Signal Modeling of Boost Converter7. Controller Design of Boost Converter8. The Controller Circuit Design of the Boost Converter using VHDL9. Simulation Verification of the Boost Controller Circuit Design10. The D/A Interface Circuit Design using VHDL11. The A/D Interface Circuit Design using VHDL12. FPGA Download Test of the Controller Design | | | |

Minghsin University of Science and Technology

Syllabus for Elective Courses

| | | | |
|---|--|---------|---|
| Course Title | Power Electronics Control System | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Ming-Fa Tsai | | |
| Course Objective | In this course, the materials about the controller and ASIC design of power electronic systems, such as buck and boost DC-DC converters, by using FPGA device and VHDL programming language are taught to the students with the help of MATLAB/Simulink simulation tool. | | |
| Text Book | “Fundamentals of Power Electronics (2nd Edition)” , Robert W. Erickson and Dragan Maksimovic, ISBN : 0-324-35365-0 | | |
| Course Contents | | | |
| <ol style="list-style-type: none">1. The Principle of Buck DC-DC Converter.2. Small-Signal Modeling of Buck Converter3. Controller Design of Buck Converter4. The Controller Circuit Design of the Buck Converter using VHDL5. Simulation Verification of the Buck Controller Circuit Design6. Small-Signal Modeling of Boost Converter7. Controller Design of Boost Converter8. The Controller Circuit Design of the Boost Converter using VHDL9. Simulation Verification of the Boost Controller Circuit Design10. The D/A Interface Circuit Design using VHDL11. The A/D Interface Circuit Design using VHDL12. FPGA Download Test of the Controller Design | | | |

Minghsin University of Science and Technology

Syllabus for Elective Courses

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|-------------------|---|---------|---|
| Course Title | System Reliability Analysis | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. Jie-Ren Shie | | |
| Course Objective | Teach students how to conduct reliability analysis from system level points of view | | |
| Text Book | N/A | | |

Course Contents

| Topics | Abstract | Hours |
|---|---|-------|
| Introduction | Introduction to reliability engineering | 6 |
| FMEA and Applications of FMEA | 1. Overview of FMEA 2. Applications and examples of FMEA | 6 |
| Theory and Mathematics of Reliability Engineering | 1. Overview of probability 2. Distributions 3. Reliability related functions 4. Reliability life | 9 |
| Relex software practices | 1. Basic of Relex 2. I/O and format of Relex files 3. Example | 9 |
| Reliability Block Diagram | 1. Overview of RBD 2. Example of RBD | 6 |
| Relex software practices of RBD applications | RBD excises | 6 |
| Fault Tree and Event Tree | 1. Overview of FT and ET 2. Example of FT and ET | 3 |
| Weibull Analysis | 1. Overview of Weibull analysis 2. Examples and excises | 9 |

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Syllabus for Elective Courses

| | | | |
|--|--|---------|---|
| Course Title | Special Topics of Semiconductor | Credits | 3 |
| | Technology | Hours | 3 |
| Instructor's Name | Dr. Chin -An Wang | | |
| Course Objective | <ol style="list-style-type: none"> 1. Introduction to semiconductor materials. 2. Introduction to semiconductor fabrication processes 3. Applications of semiconductor technology | | |
| Text Book | N/A | | |
| <p>Course Contents</p> <ol style="list-style-type: none"> 1. Introduction to semiconductor material 2. Properties of semiconductors 3. Fabrication processes of semiconductors 4. applications of semiconductor technology | | | |

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Syllabus for Elective Courses

| | | | |
|-------------------|--|---------|---|
| Course Title | Introduction to Robotics | Credits | 3 |
| | | Hours | 3 |
| Instructor's Name | Dr. JEN, FU-HUA | | |
| Course Objective | Instruct students into robotic field with interests. Both practice and theory are studied in class. Let students learn the technology and trend of robotics. | | |
| Text Book | to be assigned | | |

Course Contents

1. Requirements for mechatronics
2. Homogeneous transformation matrix
3. Coordinate transformation for robotics
4. Robot dynamics
5. Practice of industrial robot, I
6. Practice of industrial robot, II
7. Automation design of robots
8. Applications of sensors
9. Practice of intelligent robot, I
10. Path planning
11. Practice of intelligent robot, II
12. Applications of machine vision
13. Practice of intelligent robot, III
14. Bipedal robot
15. Topics of society with robots